

# The Art of Modeling Financial Options: Monte Carlo Simulation

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## Abstract

Modeling is important because scientists investigate the world around us by building models that simulate real-world problems. Modeling is neither science nor mathematics; it is the craft that builds bridges between the two. Progress in modeling dynamics has always been closely associated with advances in computing. Monte Carlo simulation/modeling or probability simulation is a technique frequently used in the financial markets to understand complex financial instruments. It is used to scrutinise the impact of risk and uncertainty in financial and other forecasting models. It is very useful when complex financial instruments need to be priced. Exotic options are listed on the JSE on its Can-Do platform. Most listed exotic options are marked-to-model and the JSE needs accurate values at the end of every day. Monte Carlo methods in a local volatility framework are implemented. This paper discusses how Monte Carlo (MC) simulation is implemented when exotic options like Barriers are valued. We further summarise the historical development in modern computing and the development of the Monte Carlo method.

*Keywords:* Exotic options, JSE, Can-Do Options, Implied Volatility, Local Volatility, Dupire Transforms, Gyöngy Theorem, Barrier options, Monte Carlo simulation, Feynmann-Kac Theorem

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## 1. Introduction

Why is simulation or modeling an important component of analysis for scientists? Simulation is the imitation of a real-world process or system. The “joy of simulation” is that one does not need to own or rent a Boeing 777 or Airbus A380 to fly them! Simulation games are fun too and one gains valuable experience at the same time. Experience and insight are gained by simulating the valuation of financial products, constructing portfolios and testing trading rules (McLeish, 2005). Through simulation work is transferred to a computer. Models can be handled that involve greater complexity and fewer assumptions, and a more faithful representation of the real world is possible. Morrison (2008) states that modeling is neither science nor mathematics; it is the craft that builds bridges between the two.

Modeling is important because scientists investigate the world around us by building models that simulate real-world problems. Our insight in a physical system, combined with numerical mathematics, gives us the rules for setting up an algorithm (the model), or a set of rules for solving a particular problem (Steinhauser, 2013). These models usually take the form of differential equations that have to be solved to obtain physical answers. Researchers usually start with a very simplistic model and try to solve it analytically or algebraically. Such models are mostly easier to analyse and scrutinise. This inevitably means they have to make a lot of simplifying assumptions. As they start to understand the dynamics of this “toy” model, they add more complexity to make it more representative of the real world problem under investigation — after theory encounters fact, the modelers revise their equations and computer programs. This means that modeling practitioners need to be familiar with a wide variety of mathematical specialities, computer science and one or more disciplines which provide data.

This is exactly the route the evolution of the Black-Scholes option pricing model took. Black, Scholes and Merton made some simplifying assumptions that enabled them to devise a backward parabolic partial differential equation (PDE). Black & Scholes (1973) used a bond and hedge replication strategy to derive their PDE while Merton (1973) made this argument more rigorous and general. They solved this PDE analytically using Fourier series methods.

It is now well-known that this model is far from the real world and stock prices behave in a much more complex manner. Black (1988) discussed the deficiencies and Kotzé (2003) emphasised the consequences of this simple model. Since 1973 most of the original simplifying assumptions have been relaxed. When some of these assumptions are relaxed, one finds that the model cannot be solved analytically anymore. This is, however, not discouraging because simulation and modeling techniques are usually great “complex problem solvers.”

Monte Carlo simulation has become an essential tool in the pricing of derivative securities and the management of risk. Most problems where there is significant uncertainty, can be solved using Monte Carlo techniques. Monte Carlo methods are techniques utilising random numbers and probability to solve problems. The analysis is based on artificially recreating a chance process, running it many times and directly observing the results. Glassermann (2004) states it is thus based on the

analogy between probability and volume.

Monte Carlo methods are attractive in evaluating integrals in high dimensions (Glassermann, 2004). What does this have to do with financial engineering? The foundation of the theory of derivative pricing is the random walk of asset prices. This is known as the Black-Scholes theory and leads to the Black-Scholes parabolic partial differential equation (PDE). According to the Feynman-Kac theorem, the solution to this PDE can be represented by an expected value — valuing derivatives is reduced to computing expectations. Monte Carlo simulation is widely used in statistics in calculating an expected value of a particular function. Boyle (1977) showed that all financial options are always the expected value of certain functions. If we were to write the relevant expectation as an integral, we would find that its dimension is large or infinite. This is precisely the setting in which Monte Carlo methods become attractive (Glassermann, 2004).

Weber (2011) stated that the Monte Carlo method is widely used in the financial markets as a valuation tool. It is used with path-dependent options and in models with more than one state variable. It is sometimes preferred to finite difference or tree methods, even in situations where these methods could work well — simply because its generality and its robustness in contexts where a portfolio of options is being valued.

In this paper, we consider the Monte Carlo approach to value exotic options. The JSE has listed exotic options and structured products on their Can-Do platform<sup>1</sup>. Kotzé & Oosthuizen (2013) discussed and explained the local volatility pricing of exotic Can-Do options like Barrier options, as well as the methodologies used to determine their initial margins. Local volatility models have been in use since the 1980s although these were not known by the name “local volatility.” The mathematical framework for local volatility was first formulated by Dupire (1994). At the same time, Derman & Kani (1994) and Rubinstein (1994) solved this problem numerically by implementing binomial trees. These methods have subsequently been improved by many other researchers (Andersen & Andreasen, 2000; Lagnado & Osher, 1997). It has since been realised that Dupire’s framework is an extension of research done by Gyöngy (1986).

Many exotic options, like Barrier options, have Black-Scholes type closed form valuation formulas (Rubinstein & Reiner, 1991; Haug, 2007; Bouzoubaa & Osserein, 2010). However, it is also known that these formulas do not lead to market related and realistic prices and hedge ratios. This is due to the assumption of a fixed volatility. However, such options are path-dependent meaning that the actual path the stock takes to get to the expiry value on the expiry date does matter. To price them correctly one should either use stochastic volatility models or local volatility models. The choice here is to use either finite difference techniques or Monte Carlo simulation. This note will focus on Monte Carlo techniques.

The layout of this paper is as follows: In section 2 we give some history on the

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<sup>1</sup>[http://www.jse.co.za/Products/Equity-Derivatives-Market/Equity-Derivatives-Product-Detail/Can-Do\\_Futures\\_and\\_Options.aspx](http://www.jse.co.za/Products/Equity-Derivatives-Market/Equity-Derivatives-Product-Detail/Can-Do_Futures_and_Options.aspx)

origins of computing and Monte Carlo simulation. Section 3 gives a brief overview of exotic options. In section 4 we bring local volatility into the Black-Scholes framework and we discretise the Black-Scholes stochastic differential equation. Section 5 is crucial where we show how to use Monte Carlo simulation when pricing options. Section 6 discusses Dupire’s local volatility mapping and in section 7 we use Dupire to price a single barrier option. We conclude in section 8.

Note that there are three Appendices where we elaborate on some of the theory described in this paper. Appendix A shows why Monte Carlo simulation can be used when pricing options and we show how to discretise the Black-Scholes stochastic differential equation. In Appendix B we discuss the generation of random numbers and in Appendix C we elaborate on convergence issues when simulating stock price paths and option values.

## 2. A Lesson in History

Progress in modeling dynamics<sup>2</sup> has always been associated with advances in computing (Morrison, 2008). As such dynamics has reached maturity with the development of digital computers, both as concept and technological product.

But, why is reading the history of science important? Donald Knuth motivates, why, as a computer scientist he reads the history of science. First, reading history helped him to understand the process of discovery. Second, understanding the difficulty and false starts experienced by brilliant historical scientists in making discoveries that specialists now find obvious helped him to see what made concepts challenging to students and thus to become a “much better writer and teacher.” Third, appreciating the historical contribution of non-Western scientists helped in “celebrating the contributions of many cultures.” Fourth, history is the craft of telling stories, which is “the best way to teach, to explain something.” Fifth, the biographies of scientists teach tactics for a successful and rewarding career. Sixth, history teaches how human experience has changed over time. As humans we should care about that (Haigh, 2015).

### 2.1. A bit of Computing History

The modern history of computing is quite short (Copeland, 2008). In 1623. Wilhelm Schickard (1592-1635), constructed a machine for his mathematician friend Johannes Kepler (1571-1630) which was able to perform addition, subtraction, multiplication and division (Steinhauser, 2013).

Charles Babbage (1792-1871) is generally credited with originating the concept of a programmable computer (Dasgupta, 2014). Babbage built a small working model in 1822 but he never completed a full-scale machine. We had to wait until 1990 when the Science Museum<sup>3</sup> in London built Babbage’s Difference Engine No. 2 from his original designs (Swade, 2005). The punch card was developed by Hermann Hollerith (1860-1929) during 1890. It was developed for a population census.

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<sup>2</sup>Dynamic means changing. Dynamical is what concerns change.

<sup>3</sup><http://www.sciencemuseum.org.uk/onlinestuff/stories/babbage.aspx>

John Atanasoff (1903-1995) is now recognised as the inventor of the first electronic computer — a special-purpose equation solver. His graduate student at the Iowa State College, Clifford Berry (1918-1963) played a big part in this. This computer was not programmable but a full-scale machine was built in 1942. It was known as the Atanasoff-Berry Computer (ABC).

Turing (1936), at Cambridge University, invented the principle of the modern computer. He described an abstract digital computing machine consisting of a limitless memory and a scanner that moves back and forth through the memory, symbol by symbol, reading what it finds and writing further symbols. He further stated that the actions of the scanner are dictated by a program of instructions that is stored in the memory in the form of symbols. This is Turing's stored-program concept, and implicit in it is the possibility of the machine operating on and modifying its own program.

Alan Turing (1912-1954) designed the Bombe. The Bombe was a device used by British cryptologists to help decipher German Enigma-machine-encrypted secret messages during World War II. It was built in 1939 and was an electro-mechanical special purpose computing device. 'Electro-mechanical' because it works using both mechanics and electricity and 'special purpose' because it can't be used to solve any other problem than the one it was designed for.

The second world war brought much needed progress though. Both the British and Americans developed electronic computing machines. The first fully functioning electronic digital computer was Colossus, used by the Bletchley Park and British cryptanalysts from February 1944. Colossus was designed by the engineer Tommy Flowers (1905-1998) and enabled the British to read high-level German army messages during World War II. The Colossus computer was built on the theoretical framework set by Turing (1936). Colossus had two problems: First, it had no internally stored programs. To set it up for a new task, the operator had to alter the machine's physical wiring, using plugs and switches. Second, Colossus was not a general-purpose machine, being designed for a specific cryptanalytic task involving counting and Boolean operations.

The first programmable computer was the ENIAC (Electronic Numerical Integrator and Computer) created by John Mauchly (1907-1980) and J. Presper Eckert (1919-1995) in 1943 at the University of Pennsylvania in Philadelphia in the USA (Haigh et al., 2014). The primary function for which ENIAC was designed was the calculation of tables used in aiming artillery. The ENIAC was somewhat similar to the earlier Colossus, but considerably larger but more flexible (Istrail & Marcus, 2013).

These earliest large-scale electronic digital computers, the Colossus and the ENIAC, did not store programs in memory. To set up these computers for a fresh task, it was necessary to modify some of the machine's wiring, re-routing cables by hand and setting switches. The basic principle of the modern computer — the idea of controlling the machine's operations by means of a program of coded instructions stored in the computer's memory — was conceived by Alan Turing (Dyson, 2012).

These machines were massive which led the IBM chairman, Thomas Watson, to state in 1943 that there might be a world market for five computers and no more (Steinhauser, 2013). With the development of the FORTRAN compiler during 1956,

modeling and simulation became a lot easier and accessible.

## 2.2. *The History of Monte Carlo Simulation*

The ‘Monte Carlo’ method was developed by the physicists and mathematicians working on the Manhattan Project<sup>4</sup> during the second world war. The main character was Stanislaw Ulam (1909-1984). Ulam and Edward Teller (1908-2003) developed the first thermonuclear weapon also known as the hydrogen bomb or H-bomb. Ulam was intensely interested in random processes. He relaxed by playing solitaire and poker. The name ‘Monte Carlo’ was coined by Nicholas Metropolis (1915-1999) during 1947 because Ulam had often mentioned his uncle, Michal Ulam, “who just had to go to Monte Carlo” to gamble.

It all started in October 1943 when Ulam received an invitation to join the Manhattan Project at the secret Los Alamos Laboratory in New Mexico. His extensive mathematical background made him aware that statistical sampling techniques had fallen into desuetude because of the length and tediousness of the calculations. It is believed that the first real application of the ‘statistical sampling method’ was undertaken by Enrico Fermi (1901-1954) in the 1930s. Due to the computational issues, this method did not really take off.

But, Los Alamos had access to the ENIAC. Access to this toy convinced Ulam that Fermi’s statistical techniques should be resuscitated, and he discussed this idea with John von Neumann (1903-1957) — a principle member of the Manhattan Project<sup>5</sup>. This triggered the spark that led to the Monte Carlo method. One of the first problems solved on the ENIAC in 1946 was a computational model of a thermonuclear reaction<sup>6</sup>. Metropolis & Ulam (1949) published the first unclassified paper on the Monte Carlo method in 1949.

Los Alamos got its own computer early in 1952. It was called the MANIAC (Mathematical Analyzer, Numerical Integrator, and Computer or Mathematical Analyzer, Numerator, Integrator, and Computer). Enrico Fermi joined Los Alamos during the summer of 1952 and used the MANIAC to solve many statistical problems. A significant advance in the use of the Monte Carlo method came out of the collaboration between Nicholas Metropolis and Edward Teller. Together they introduced the idea of what is today known as importance sampling, also referred to as the Metropolis algorithm<sup>7</sup>.

## 2.3. *Monte Carlo Methods and the Pricing of Options*

Boyle (1977) was the first to relate the pricing of options to the simulation of random asset paths. He showed how to find the fair value of an option by generating

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<sup>4</sup>[http://en.wikipedia.org/wiki/Manhattan\\_Project](http://en.wikipedia.org/wiki/Manhattan_Project)

<sup>5</sup><http://library.lanl.gov/cgi-bin/getfile?00326866.pdf>

<sup>6</sup>A thermonuclear reaction or nuclear fusion is the fusion of two light atomic nuclei into a single heavier nucleus by a collision of the two interacting particles at extremely high temperatures, with the consequent release of a relatively large amount of energy. This reaction is responsible for the energy produced in the sun.

<sup>7</sup><http://library.lanl.gov/cgi-bin/getfile?00326886.pdf>

lots of possible future paths for an asset and then looking at the average that the option had paid off. The future important role of Monte Carlo simulations in finance was assured. Longstaff & Schwartz (1991) and Broadie & Glasserman (1997) showed us how to value American options using Monte Carlo simulation. Boyle et al. (1997) discussed the general pricing of securities using Monte Carlo methods.

### 3. Exotic Options

Two questions come to mind, “what is an exotic option” and, “what is a structured product?” Simply put, an exotic option is any type of option other than the standard calls and puts found on major exchanges. We can narrow this definition down slightly, by stating that exotic options are options for which payoffs at maturity cannot be replicated by a set of standard options (de Weert, 2008). Further to this, a structured derivative product is a bespoke instrument that enables an investor to pursue strategies tailored to his or her market view (Tan, 2010). Such a product allows an investor more control over the yield-risk tradeoff in his investment.

Exotic options and structured notes have traditionally been traded over-the-counter (OTC). The JSE was the first exchange in the world to list such products. Since 2007, the types of exotic listed on the JSE have grown tremendously. Most exotic options are European in nature — this means they can only be exercised on the expiry date. Most equity exotics have the FTSE/JSE Top 40 Index (ALSI) and FTSE/JSE Shareholders Weighted Top 40 Index (DTOP) indices as underlying instruments. On the foreign exchange side, the USDZAR is the preferred underlyer due to its massive liquidity.

If an instrument is liquid, a full mark-to-market (MtM) process can be run because on-screen traded prices or bid-ask spreads are available. However, all exotic instruments are very illiquid, and a mark-to-model process is used. This means models are used in estimating the end of day levels. In this note, we will describe how these exotic instruments can be evaluated using Monte Carlo simulation.

### 4. Solving the Generalised Black-Scholes PDE

#### 4.1. Deterministic Local Volatility

One of the original assumptions made by Black, Scholes and Merton was that volatility is constant. We can generalise the standard Black-Scholes stochastic differential equation (SDE) by assuming that volatility is dependent on the asset’s price and time (it’s not constant anymore) but we still assume it to be deterministic. If we do this we get

$$dS_t = \mu S_t dt + \sigma(S_t, t) S_t dW_t. \quad (4.1)$$

Remember,  $W_t$  is a standard Brownian motion and as such  $dW_t = \varepsilon \sqrt{dt}$  where  $\varepsilon \sim N(0, 1)$ ,  $N(0, 1)$  being a standardised normal distribution. Further,  $S_t$  is the price of the underlying stock,  $t$  is the time and  $\mu$  is a drift parameter.

In Equation (4.1), the function  $\sigma(S, t)$  is called the local volatility function because it is dependent on both  $S$  and  $t$ . Note that  $\sigma(t)$  is sometimes referred to as the

instantaneous volatility — it is a function of time only. See Kotzé et al. (2015) for a full description and explanation of the concept of local volatility. The local volatility is the instantaneous volatility for each point in space and time i.e., it is the volatility that holds near the point when the stock’s value is  $S_t$  at a time  $t$ . It is the volatility that is ‘local’ to the point  $(S_t, t)$  — ‘local’ defined in a similar fashion to the ‘local’ in ‘local extrema’. Further to this definition, this description is similar to the definition of a ‘field’ in physics. In physics, a ‘field’ is a physical quantity that has a value for each point in space and time. In this case, local volatility is a scalar field (Boas, 1983; Reif, 2008). These concepts come from *mean field theory* (MFT) where the *Ising* model is a standard many-body system discussed in solid state physics textbooks (Harras, 2012; McCauley, 2013; Sornette, 2014).

Please note that the basic Black-Scholes assumptions still hold: the asset price  $S_t$  evolves log-normally,  $\mu$  is the expected continuously compounded rate of return earned by an investor in a short period of time  $dt$  — the instantaneous expected return and  $W_t$  is a standard Brownian motion or Wiener process. It is clear that  $W$ , and consequently its infinitesimal increment  $dW_t$ , still represents the only source of uncertainty in the price history of the security.

Black, Scholes and Merton made some assumptions in order to facilitate a better understanding of the dynamics of the security price  $S_t$ . One of the main assumptions is that of risk neutrality. In its simplest form, this infers that all risk-free portfolios can be assumed to earn the same risk-free rate. We can then put  $\mu = r_t - d_t$  where  $r_t$  is a deterministic interest rate (it can be obtained from a relevant yield curve) and  $d_t$  is a deterministic dividend yield. Under these assumptions, the risk-neutral dynamic of the asset is (Hull, 2012)

$$dS_t = (r_t - d_t)S_t dt + \sigma(S_t, t)S_t dW_t. \quad (4.2)$$

To move forward and obtain the price of an option, we let a scalar function  $V_l(S, t)$  be the value of a contingent claim like an option at any time  $t$  conditional on the price of the underlying being  $S_t$  at that time. Using Ito’s lemma, equation (4.2) can be transformed to the generalised Black-Scholes stochastic partial differential equation (PDE)

$$\frac{\partial V_l}{\partial t} + \frac{1}{2}\sigma^2(S_t, t)S_t^2 \frac{\partial^2 V_l}{\partial S_t^2} + (r_t - d_t)S_t \frac{\partial V_l}{\partial S_t} - r_t V_l = 0. \quad (4.3)$$

Equation (4.3) basically describes how the value of a derivative contract, at a continuum of potential future scenarios, diffuses *backwards* in time towards today. This equation is a backward parabolic partial differential equation also known as the *backward Kolmogorov* equation (Rebonato, 2004; Duffie, 1996). This is just an extension of Joseph Fourier’s one-dimensional heat conduction equation formulated in 1822 (Narasihan, 1999).

#### 4.2. Discretising the Black-Scholes Equation

Fourier solved his simplistic heat conduction equation analytically by introducing Fourier transforms. The extended version is not solved that easily. However, we will understand the SDE in Equation (4.2) much better if we make a change of variables.



Let's re-write (4.2) in terms of  $\ln(S)$  and then a simple application of Itô's lemma gives

$$S_T = S_0 \exp \left( \left( (r_T - d_T) - \frac{1}{2} \sigma^2(S_T, T) \right) T + \sigma(S_T, T) \varepsilon \sqrt{T} \right). \quad (4.4)$$

Note,  $\varepsilon \sim N(0, 1)$ ,  $N(0, 1)$  being a standardised normal distribution. See Appendix A for the derivation. Equation (4.4) formulates a way to obtain the terminal value of the stochastic process  $S$ . This, together with equations (5.8) and (5.9) (see section 5 below) can now be used to obtain the value of our option  $V(S, t)$ .

Equations (4.2) and (4.4) are both defined for a continuous time variable  $t$ . So the question is how do we sample from the continuous distribution for the variable  $S_T$ ? These equations can be discretised by using the Euler scheme (Jäckel, 2002; Glassermann, 2004). This leads to

$$S(t_{i+1}) = S(t_i) \exp \left[ \left( (r(t_i) - d(t_i)) - \frac{\sigma^2(S(t_i), t_i)}{2} \right) \Delta t + \sigma(S(t_i), t_i) \varepsilon_t \sqrt{\Delta t} \right]. \quad (4.5)$$

Here,  $i = 1, 2, \dots, N$  such that  $t_i = i\Delta t$  and  $T = N\Delta t$ . In order to start the simulation we need a starting asset value  $S(t_0)$ . If we then know the input parameters like the volatilities, risk-free rates and dividend yields, we can estimate a price for  $S$  at each discretised step  $i$  until we reach  $S(t_N) = S(T)$ . Such a price path is shown in Figure 1 where we have 25 time steps.

The Euler scheme can be improved if we include the next order terms of the Itô-Taylor expansion of Equation (4.2). This gives (Jäckel, 2002; Glassermann, 2004; Clark, 2011)

$$S(t_{i+1}) = S(t_i) \exp \left[ \left( (r(t_i) - d(t_i)) - \frac{\sigma^2(S(t_i), t_i)}{2} [\varepsilon_t^2 - 1] \right) \Delta t + \sigma(S(t_i), t_i) \varepsilon_t \sqrt{\Delta t} \right]. \quad (4.6)$$

$\varepsilon_t$  is sampled from a standardised normal distribution — this is further discussed in Appendix B. By adding a term where the diffusion is  $O(\Delta t)$  we get convergence of strong order 1. One of the advantages of Milstein over Euler time stepping is improved convergence when  $\Delta t$  is infinitesimal. In that case we can take larger time steps and get by with a smaller number of time steps  $N$ .

## 5. From Black-Scholes to Monte Carlo Simulation

Let's assume  $V_l(S_T, T)$  is the final condition of our contingent claim at expiry  $T$  and, given that the process,  $S$ , starts at  $S_0$  at initial time  $t_0$ . The general solution to the Black-Scholes backward parabolic partial differential equation in Equation (4.3) is given by the Feynman-Kac theorem stating

$$V_l(S_0, t_0) = E^{\mathbb{Q}} \left[ e^{-\int_{t_0}^T r_u du} V_l(S_T, T) | S_{t_0} = S_0 \right], \quad (5.7)$$

where  $S, t \in \mathbb{R}_0^+$  and  $S_t$  is described by the stochastic differential Equation (4.2) and  $r_u$  is the instantaneous discount rate applicable for a very short period of time



Figure 1: A price path for a security with price R100 at time  $t = t_0$ , risk-free rate  $r = 0.05$ , dividend yield  $d = 0.025$  (both continuous), volatility of 15% and  $T = 0.5$ . Further,  $N = 25$  and then  $\Delta t = 0.02$

$du$  (Linetsky, 1998; Duffie, 1996). Note that the expectation is taken under the risk-neutral probability measure  $\mathbb{Q}$  where the stochastic term in Equation (4.2) is governed by Brownian motion or a Wiener process. Note that the Feynman-Kac theorem provides the justification for the practice of evaluating today's value of an option ( $V_i(S_0, t_0)$ ) as the discounted expectation of its terminal payoff.

Using the mathematical law of expectation, the expectation for a call option in Equation (5.7) can be written as an integral such that (Duffie, 1996; Wilmott, 2000)

$$V(S, t) = e^{-r_T(T-t)} \int_K^\infty \max[0, (S_T - K)]g(S_T)dS_T \quad (5.8)$$

where  $g(S_T)$  is the probability density function (pdf) of  $S_T$  and we assume  $\ln(S_T)$  is normally distributed with a standard deviation of  $w$ . We thus need to integrate over all possible  $S$ -values that is larger than the strike  $K$  at expiry. For a put we have

$$V(S, t) = e^{-r_T(T-t)} \int_0^K \max[0, (K - S_T)]g(S_T)dS_T. \quad (5.9)$$

Remember  $K, S \in \mathbb{R}_0^+$

Using equations (5.8) and (5.9), we show in Appendix A.5 that these equations can be discretised such that the simplest Monte Carlo method to price an option is

given by

$$V_{MC}(S, t) = e^{-rT(T-t)} \frac{1}{M} \sum_{i=1}^M \max[0, \phi(S_T - K)] \quad (5.10)$$

where  $S_T$  is attained after  $N$  time steps that coincide with the expiry time  $T$ . We can use either Equation (4.5) or Equation (4.6) to estimate  $S_T$ . To obtain the Monte Carlo option price, we need to obtain  $M$ ,  $S_T$  values. This means we simulate  $S_T$ ,  $M$  times to obtain the average option value  $V_{MC}$ . Note:  $N$  is the number of time steps and  $M$  the number of simulations.

By scrutinising equations (5.10), (4.5) and (4.6) it becomes clear that MC methods are indeed techniques utilising random numbers and probability to solve problems. It is evident that such an analysis is based on artificially recreating a chance process, running it many times and directly observing the results.

Figure 2 shows 5 price paths generated with Equation (4.5), each having 25 time steps. Here we have a fixed volatility, interest rate and dividend yield (in the limit as  $M \rightarrow \infty$ , all  $S_T$ 's will have a normal distribution). If we have a call option with a strike price of 100, Equation (5.10) leads to an option value of R11.02. This is shown in Table 1.

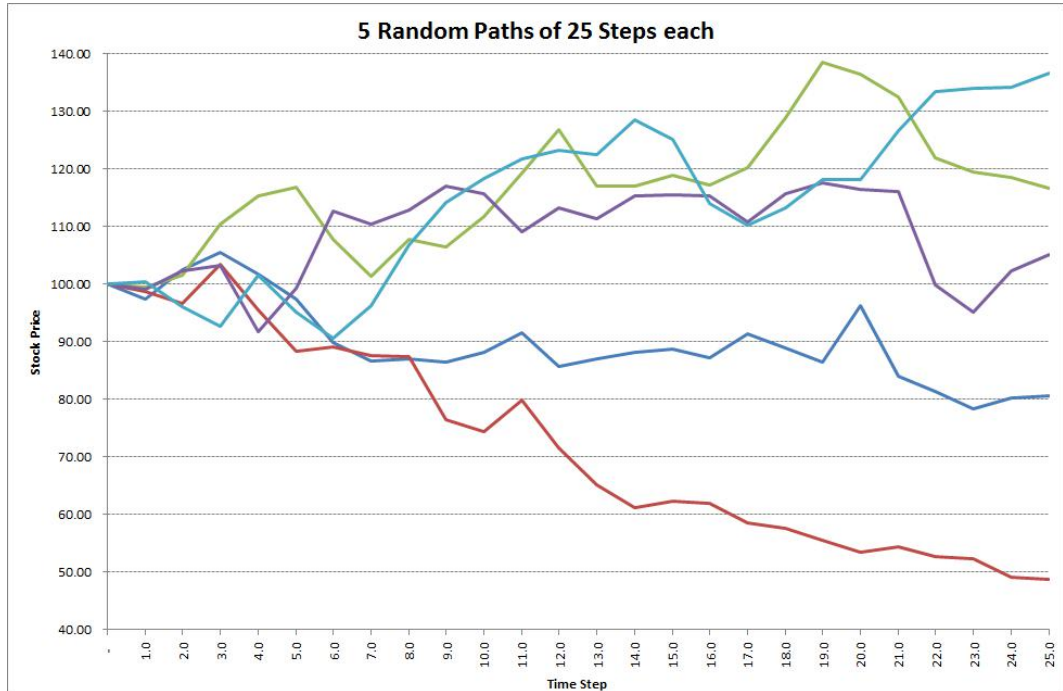


Figure 2: Price paths for a security with price R100 at time  $t = t_0$ , risk-free rate  $r = 0.05$ , dividend yield  $d = 0.025$  (both continuous), volatility of 0.25 and  $T = 1.0$ . Further,  $N = 25$  and then  $\Delta t = 0.04$  and  $M = 5$

In the example above we used a fixed volatility of 25%. However, crucial to obtaining the correct terminal values  $S_T$  is that the volatilities we use in equations (4.5) and (4.6) are the volatilities obtained from a local volatility surface. We thus need to understand what we mean by the time stamp in the local volatility  $\sigma(S(t_i), t_i)$

<b>Time Steps</b>	<b><math>S</math> Path 1</b>	<b><math>S</math> Path 2</b>	<b><math>S</math> Path 3</b>	<b><math>S</math> Path 4</b>	<b><math>S</math> Path 5</b>
t=0	100.00	100.00	100.00	100.00	100.00
1.0	97.49	98.66	99.55	99.19	100.42
2.0	102.50	96.74	101.50	102.40	96.10
3.0	105.45	103.45	110.48	103.19	92.63
4.0	101.84	95.56	115.39	91.72	101.54
5.0	97.43	88.44	116.87	99.39	95.19
6.0	89.92	89.17	107.82	112.78	90.70
7.0	86.61	87.65	101.33	110.39	96.34
8.0	87.03	87.35	107.89	112.91	106.92
9.0	86.52	76.50	106.55	117.03	114.14
10.0	88.12	74.35	111.81	115.73	118.42
11.0	91.51	79.93	119.28	109.11	121.68
12.0	85.74	71.59	126.84	113.27	123.20
13.0	87.00	65.09	117.05	111.47	122.55
14.0	88.18	61.22	117.10	115.39	128.60
15.0	88.78	62.40	118.89	115.56	125.20
16.0	87.23	61.89	117.24	115.35	113.94
17.0	91.47	58.64	120.21	110.88	110.23
18.0	88.94	57.62	128.98	115.69	113.36
19.0	86.45	55.57	138.58	117.54	118.14
20.0	96.29	53.43	136.41	116.45	118.08
21.0	84.00	54.48	132.53	116.12	126.71
22.0	81.40	52.66	121.86	99.82	133.38
23.0	78.38	52.31	119.51	95.14	134.03
24.0	80.22	49.19	118.52	102.38	134.16
25.0 ( $S_T$ )	80.68	48.68	116.72	105.11	136.68
<b>Call Value at <math>T</math></b>	<b>0.00</b>	<b>0.00</b>	<b>16.72</b>	<b>5.11</b>	<b>36.68</b>
<b>Average Value</b>	<b>11.70</b>				
<b>Value Today</b>	<b>11.02</b>				

Table 1: Five price paths and the Monte Carlo option price for a vanilla call. The parameters are given below Figure 2

in these equations. This shows we first of all need the stock price at each time step, i.e.,  $S(t_i)$ . We have given some examples in Table 1. But, further to this, we also need the instantaneous volatility at each time step for each stock price. We can obtain all of this from a three dimensional local volatility surface. We will discuss this in section 6 below.

## 6. Dupire’s Local Volatility Mapping

Local volatility models are widely used in the finance industry (Engelmann et al., 2009). Whereas stochastic volatility and jump-diffusion models introduce new risks into the modeling process, local volatility models stay close to the Black-Scholes theoretical framework and only introduce more flexibility to the volatility. This is one of the main reasons of fierce criticism of local volatility models (Ayache et al., 2004). Thus, it is a mistake to interpret local volatility as a complete representation of the true stochastic process driving the underlying asset price. Local volatility is merely a simplification that is practically useful for describing a price process with non-constant volatility. A local volatility model is a special case of the more general stochastic volatility models. That is why these models are also known as “*restricted stochastic volatility models*”.

### 6.1. Dupire’s Formula

The local volatility function  $\sigma(S, t)$  is assumed to be deterministic — it is a deterministic function of a stochastic quantity  $S_t$  and time. So there is still just one source of randomness, ensuring that the completeness of the Black-Scholes model is preserved. Completeness is important, because it guarantees unique prices, thus arbitrage pricing and hedging (Dupire, 1993).

Dupire (1994) was the first to show algebraically that, given prices of European call or put options across all strikes and maturities, we may deduce the volatility function  $\sigma(S, t)$ , which produces those prices via the full Black-Scholes equation (Clark, 2011). Dupire’s insight was that if the spot price follows a risk-neutral random walk and if no-arbitrage market prices for European vanilla options are available for all strikes and expiries, then the local volatility  $\sigma(S, t)$  in Equation (4.1) can be extracted analytically from European option prices (Dupire, 1993). He, unknowingly, applied Gyöngy’s theorem (Gyöngy, 1986).

Dupire showed that if we have implied or market volatilities, we can calculate the local volatilities thereof where (Wilmott (1998) and Clark (2011))

$$\sigma_{loc}^2(S_0, K, \tau) = \frac{\sigma_{imp}^2 + 2\tau\sigma_{imp}\frac{\partial\sigma_{imp}}{\partial\tau} + 2(r-d)K\tau\sigma_{imp}\frac{\partial\sigma_{imp}}{\partial K}}{\left(1 + Kd_1\sqrt{\tau}\frac{\partial\sigma_{imp}}{\partial K}\right)^2 + K^2\tau\sigma_{imp}\left(\frac{\partial^2\sigma_{imp}}{\partial K^2} - d_1\sqrt{\tau}\left(\frac{\partial\sigma_{imp}}{\partial K}\right)^2\right)}, \quad (6.11)$$

where

$$d_1 = \frac{\ln(S_0/K) + ((r-d) + \sigma_{imp}^2/2)\tau}{\sigma_{imp}\sqrt{\tau}},$$

and  $\tau = T - t$  such that  $t$  and  $S_0$  are respectively the market date, on which the volatility smile is observed, and the asset price on that date. Note that Equation (6.11) gives the variance, i.e.,  $\sigma^2$ . See Kotzé et al. (2015) for the derivation.

The main problem is that the implied or traded volatilities are only known at discrete strikes  $K$  and expiries  $T$ . This is why the parameterisation chosen for the implied volatility surface is very important. If implied volatilities are used directly from the market, the derivatives in Equation (6.11) needs to be obtained numerically using finite difference or other well-known techniques. This can still lead to an unstable local volatility surface. Furthermore we will have to interpolate and extrapolate the given data points unto a surface. Since obtaining the local volatility from the data involves taking derivatives, the extrapolated implied volatility surface cannot be too uneven. If it is, this unevenness will be exacerbated in the local volatility surface showing that it is not arbitrage free in these areas.

Kotzé et al. (2015) showed that the JSE uses a deterministic functional form for their ALSI implied volatility surface. This function is quadratic across strike and exponential across time. This three dimensional function is fitted to traded data. They further showed that all derivatives in Equation (6.11) can be obtained analytically and the ALSI local volatility surface is easy to calculate and obtain. They went further and discussed the DTOP and USDZAR implied volatility surfaces. There are no functional forms available and all derivatives in Equation (6.11) needs to be computed numerically.

### 6.2. Dupire and Monte Carlo Simulation

The JSE uses Dupire’s formula in Equation (6.11) to convert the implied volatility surfaces for all vanilla options traded on all underlying future contracts to their respective local volatility surfaces. The local volatility surfaces are used when exotic options are evaluated. Exotics are mostly traded on the ALSI, DTOP and USDZAR and some single name futures.

Figures 3 and 4 show the implied and local volatility surfaces for ALSI and USDZAR options respectively on 28 May 2014.

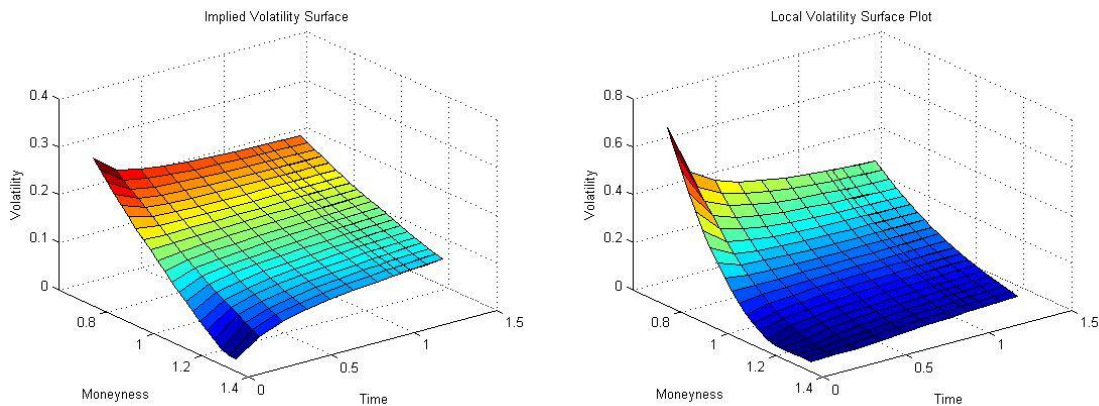


Figure 3: ALSI implied and local volatility surfaces on 28 May 2014

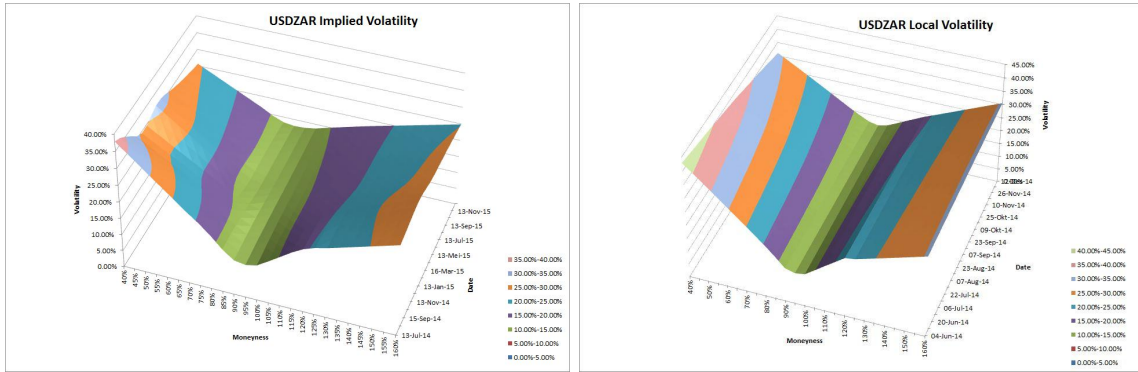


Figure 4: USDZAR implied and local volatility surfaces on 28 May 2014

From Figure 3 we notice that the implied volatility surface does not have a lot of curvature — it is skewed but flat. However, we also see from the local volatility surface that it has more curvature. This shows that the local volatility skew is twice that of the implied volatility skew. Figure 4, shows the USDZAR implied volatility surface that has the currency market’s all familiar smile. Here we also show the local volatility surface with steeper sides.

Continuing with our example: in section 5 and Table 1 we tabulated some price paths. We now want to calculate the Dupire local volatility for each stock price at each time step. This is the local volatility that should then be used in equations (4.5) and (4.6) to obtain the price paths as shown in Table 1.

On a practical note: in equations (4.5) and (4.6) we generate a stock price  $S(t_i)$  at each time step  $t_i$ . To apply Equation (6.11) we now say that  $\tau = t_i$  and  $S(t_i) = K$ . Why? To obtain the local volatility we step forward in time and at every time step assume we price an option with an expiry time of  $T$  and then  $\tau = T - t_0$  but in most cases  $t_0 = 0$ . Further, Dupire’s equation is given in terms of the strike. It holds for all strikes because  $K \in \mathbb{R}_0^+$ . We then say that  $S(t_i)$  is a possible strike at time  $t_i$  and we have  $K = S(t_i)$ .

In our example, the price paths were shown for a one year time period. The JSE/FTSE Top 40 index was 44,732 on 28 May 2014. The price paths in Table 1 were generated with a fixed volatility of 25%. We thus cannot generate the same price paths under a local volatility regime. However, to show the difference between a fixed volatility and local volatility implementation, we now use the same random numbers as before and we assume that the one year ATM volatility is 25%. So we run this experiment and generate 5 price paths under the ALSI local volatility surface. The newly generated price paths are shown in Figure 5. The actual numbers are listed in Table 2 and the corresponding local volatilities are listed in Table 3.

Comparing graphs 5 and 2 and Tables 2 and 1 reveal that the stock prices are not that much different. This is the way it should be because the local volatility does not differ that much from the implied volatility. However, even these slight differences, can lead to vastly different exotic option prices and especially, Greeks.

<b>Time Steps</b>	<b>Path 1</b>	<b>Path 2</b>	<b>Path 3</b>	<b>Path 4</b>	<b>Path 5</b>
0	100.00	100.00	100.00	100.00	100.00
<b>1.0</b>	97.49	98.66	99.55	99.19	100.42
<b>2.0</b>	102.47	96.72	101.50	102.40	96.11
<b>3.0</b>	105.44	103.41	110.49	103.20	92.60
<b>4.0</b>	101.87	95.54	115.46	91.75	101.45
<b>5.0</b>	97.47	88.40	117.03	99.35	95.11
<b>6.0</b>	89.94	89.05	108.05	112.74	90.60
<b>7.0</b>	86.57	87.46	101.58	110.41	96.17
<b>8.0</b>	86.91	87.08	108.17	112.99	106.70
<b>9.0</b>	86.32	76.20	106.87	117.18	113.95
<b>10.0</b>	87.83	73.91	112.18	115.95	118.29
<b>11.0</b>	91.15	79.29	119.74	109.38	121.63
<b>12.0</b>	85.36	70.91	127.41	113.60	123.24
<b>13.0</b>	86.54	64.32	117.68	111.86	122.68
<b>14.0</b>	87.64	60.31	117.80	115.84	128.82
<b>15.0</b>	88.17	61.26	119.67	116.08	125.53
<b>16.0</b>	86.58	60.55	118.08	115.94	114.31
<b>17.0</b>	90.73	57.18	121.15	111.50	110.65
<b>18.0</b>	88.18	55.97	130.07	116.40	113.84
<b>19.0</b>	85.67	53.78	139.87	118.31	118.70
<b>20.0</b>	95.34	51.50	137.80	117.30	118.71
<b>21.0</b>	83.16	52.30	133.99	117.03	127.47
<b>22.0</b>	80.51	50.34	123.31	100.65	134.27
<b>23.0</b>	77.44	49.80	121.01	95.94	135.04
<b>24.0</b>	79.16	46.63	120.08	103.23	135.28
<b>25.0</b>	79.53	45.94	118.33	106.00	137.92

Table 2: Price paths under a local volatility regime



$\tau = t_i$	LV Path 1	LV Path 2	LV Path 3	LV Path 4	LV Path 5
<b>0</b>	24.9996%	24.9996%	24.9996%	24.9996%	24.9996%
<b>0.04</b>	27.4866%	26.2902%	25.4045%	25.7573%	24.5469%
<b>0.08</b>	23.0088%	27.6461%	23.7543%	23.0681%	28.1790%
<b>0.12</b>	21.2633%	22.5733%	18.2763%	22.7096%	30.5823%
<b>0.16</b>	23.6806%	27.9284%	16.3403%	30.7435%	23.9482%
<b>0.20</b>	26.4488%	32.8200%	16.1544%	25.2543%	28.0043%
<b>0.24</b>	31.2864%	31.9153%	20.5232%	18.3454%	30.8294%
<b>0.28</b>	33.3024%	32.6808%	23.9452%	19.6009%	27.0274%
<b>0.32</b>	32.7299%	32.6118%	20.7567%	18.6921%	21.4314%
<b>0.36</b>	32.8310%	39.9575%	21.4424%	17.2989%	18.4947%
<b>0.40</b>	31.6159%	41.1589%	19.3257%	17.9228%	17.1125%
<b>0.44</b>	29.4515%	36.9318%	16.8225%	20.5418%	16.2359%
<b>0.48</b>	32.7295%	42.4271%	14.8280%	19.0348%	15.9505%
<b>0.52</b>	31.8303%	46.6896%	17.7768%	19.7628%	16.2770%
<b>0.56</b>	31.0305%	49.0341%	17.8591%	18.4809%	14.8622%
<b>0.60</b>	30.5979%	47.9364%	17.4077%	18.5037%	15.8216%
<b>0.64</b>	31.3536%	48.0069%	17.9798%	18.6365%	19.1543%
<b>0.68</b>	29.0183%	49.8401%	17.2056%	20.1550%	20.4486%
<b>0.72</b>	30.2556%	50.2336%	15.1812%	18.6495%	19.4400%
<b>0.76</b>	31.4912%	51.2306%	13.5589%	18.1646%	18.0554%
<b>0.80</b>	26.5871%	52.2391%	14.0215%	18.5222%	18.1259%
<b>0.84</b>	32.6223%	51.4452%	14.7868%	18.6588%	16.0669%
<b>0.88</b>	33.9686%	52.2491%	17.0924%	24.2576%	14.8494%
<b>0.92</b>	35.5782%	52.2521%	17.7223%	26.1977%	14.8259%
<b>0.96</b>	34.4757%	53.6275%	18.0146%	23.2429%	14.8868%
<b>1.00</b>	34.1544%	53.6906%	18.5148%	22.2471%	14.5786%

Table 3: The Dupire local volatilities as obtained from the ALSI local volatility surface on 28 May 2014

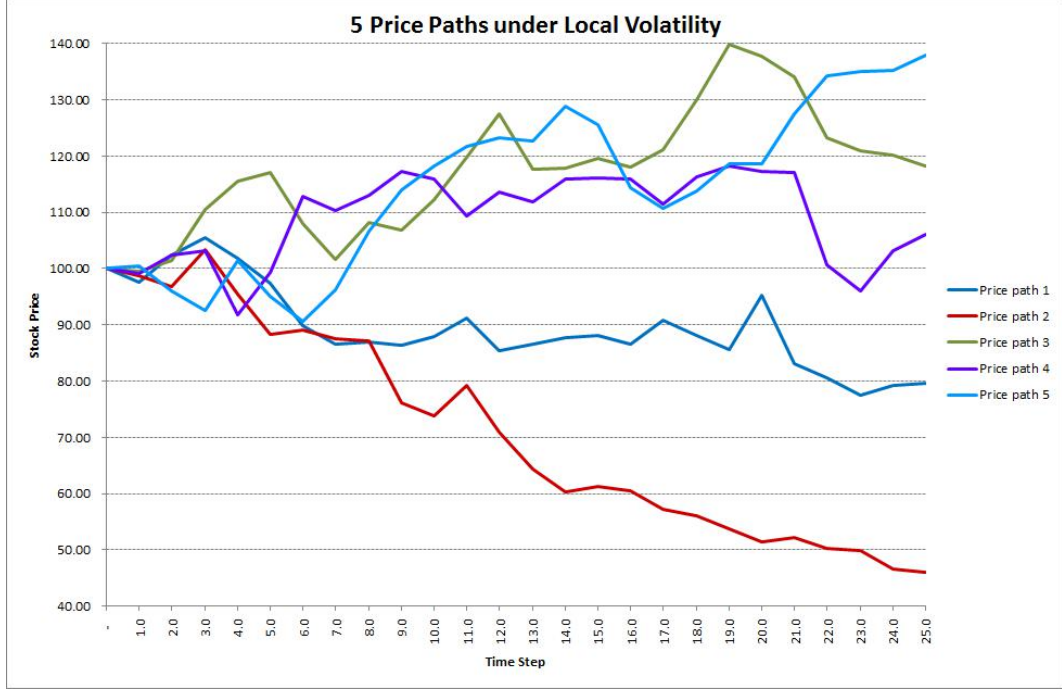


Figure 5: Price paths for a security with price R100 at time  $t = t_0$ , risk-free rate  $r = 0.05$ , dividend yield  $d = 0.025$  (both continuous) and  $T = 1.0$ . Further,  $N = 25$  and then  $\Delta t = 0.04$  and  $M = 5$ . The volatility used is the local volatility for ALSI options on 28 May 2014.

## 7. Pricing Barrier Options under Local Volatility

Let's now look at the price and hedge ratio Delta of a down-and-out put barrier option on the JSE/FTSE Top 40 index. We price this option using Monte Carlo simulation under a local volatility surface and using the closed-form solutions. Rubinstein & Reiner (1991) derived closed-form solutions to all vanilla barrier options in a Black-Scholes framework.

To explain the differences between the MC and closed-form solutions, we look at an example of a one month down-and-out put. This example's input parameters are shown in Table 4.

The payoff function for a down-and-out barrier is

$$V_{DAO}(S, t) = e^{-r_T(T-t)} \frac{1}{M} \sum_{j=1}^M \begin{cases} \max[0, \phi(S_T - K)] & \iff S(t_i) > H, t \leq T \\ R & \iff S(t_i) \leq H, t \leq T. \end{cases}$$

Monte Carlo simulation is implemented by using Equation (5.10). We can further use either Equation (4.5) or Equation (4.6) to estimate the stock price  $S(t_i)$  at each time step  $t_i$  and ultimately  $S_T$ . Having calculated the stock price at each time step  $t_i$ , makes it quite easy to implement the boundary conditions. At each time step one needs to check if the stock price  $S(t_i)$  is above or below the barrier  $H$ .

If we want to implement the closed-form solution, we need to understand that we can do it in two different ways: we first price it using a fixed volatility of 14.5% and

Description	Input Values
Equity price	44 732.00
Strike	44 732.00
Barrier	40 258.80
Rebate	0.000
Number of discrete observations	146.00
Current date	28-May-14
Maturity date	30-Jun-14
Interest Rate (NACA)	6.00%
Volatility	14.50%
Dividend Yield (NACA)	3.00%
Type of option	Down and out put

Table 4: Input parameters for a down-and-out-put option on the JSE/FTSE Top 40 index.

secondly we obtain the volatility from the implied volatility surface.

The price dynamics of this option is shown in Figure 6 where closed-form is abbreviated by CF. The barrier is 90% of the spot level and it is short dated. The price dynamics between the three methods do not differ much and using the slower Monte Carlo method does not add much value. Figure 6 shows the familiar option profile

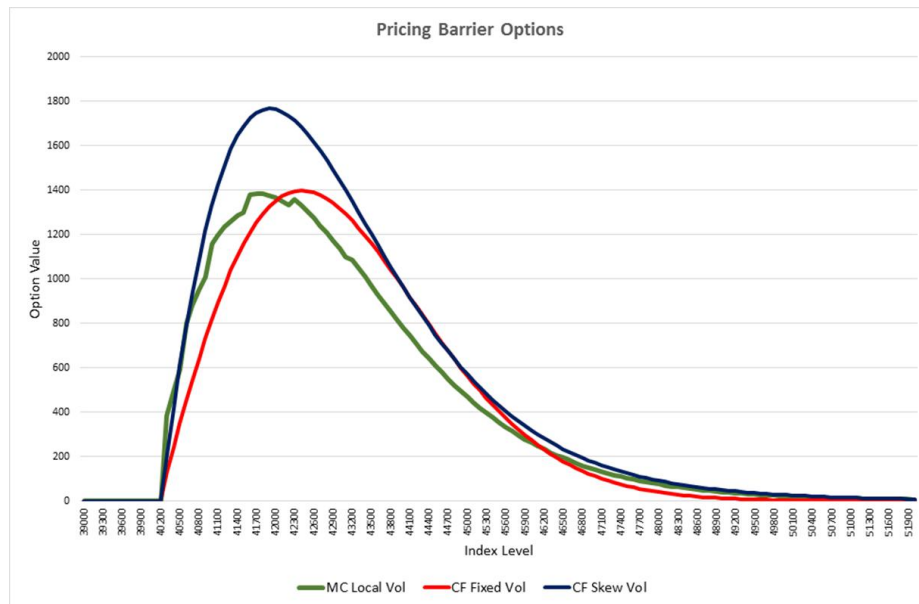


Figure 6: Price dynamics for a down-and-out-put.

for a down-and-out put option — the option vanishes if the stock price breaches the barrier level.

The dynamics of the hedge ratio Delta is shown in Figure 7. Here is where the answers differ substantially. Far from the barrier all three methods give the same

Delta. However, interestingly, close to the barrier, the closed-form solution breaks down. This is a put option and the  $\Delta$  should be negative always. The local volatility model behaves correctly and gives the correct hedge parameter even if the spot is very close to the barrier.

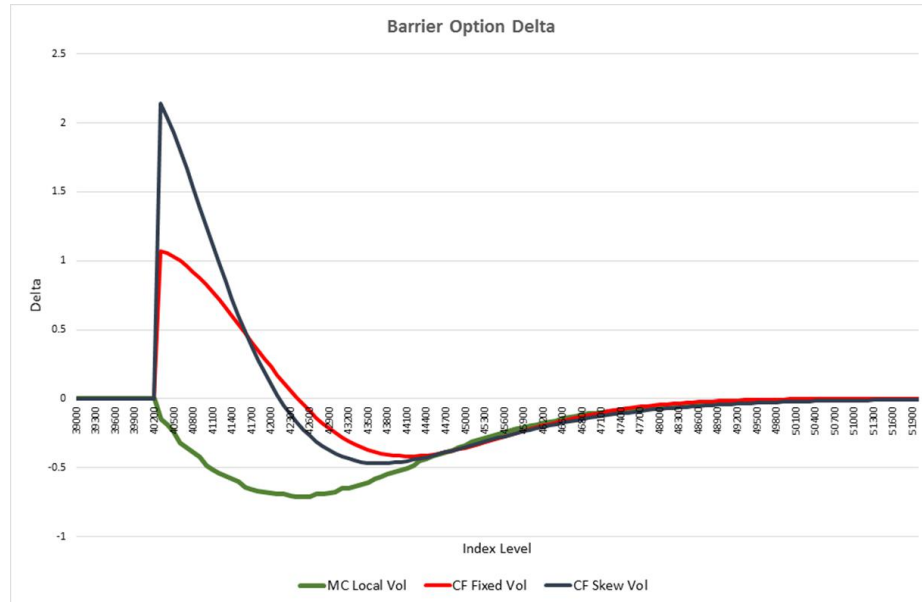


Figure 7: The  $\Delta$ -dynamics for a down-and-out-put option.

## 8. Conclusion

Monte Carlo methods are powerful and can be used to price exotic options. In this note we introduced Monte Carlo simulation and explained why it can be used to price all kinds of derivatives securities. We introduced the local volatility framework and showed how to incorporate it into a MC simulation. This was done at the hand of many examples. We concluded by explaining how a barrier option should be priced in a local volatility framework.

## Acknowledgements

Thanks are due to the JSE for data.

# Appendices

## A. From Black-Scholes to Discrete Monte Carlo Simulation

### A.1. The Feynman-Kac Theorem and Expectation

Fourier solved his simplistic heat conduction equation analytically by introducing Fourier transforms. The extended version is not solved that easily. However, the Feynman-Kac theorem can be used to solve it (Rebonato, 2004). This is possible if  $V_l(S, t)$  in Equation (4.3) is twice differentiable and  $V_l(S_T, T)$  is the terminal condition. We also have  $S_T$  being the terminal asset value on the expiry time  $T$ . The Feynman-Kac theorem establishes a link between parabolic partial differential equations and stochastic processes or diffusion problems we encounter in finance (Jäckel, 2002). It offers a method of solving certain PDEs by simulating random paths of a stochastic process (Klebaner, 2005; Clark, 2011). If we now let  $V_l(S_T, T)$  be the final condition of our contingent claim at expiry  $T$  and, given that the process,  $S$ , starts at  $S_0$  at initial time  $t_0$ , the general solution to this backward parabolic partial differential equation shown in Equation (4.3) is given by

$$V_l(S_0, t_0) = E^{\mathbb{Q}} \left[ e^{-\int_{t_0}^T r_u du} V_l(S_T, T) | S_{t_0} = S_0 \right], \quad (\text{A.12})$$

where  $S, t \in \mathbb{R}_0^+$  and  $S_t$  is described by the stochastic differential Equation (4.2) and  $r_u$  is the instantaneous discount rate applicable for a very short period of time  $du$  (Linetsky, 1998; Duffie, 1996). Note that the expectation is taken under the risk-neutral probability measure  $\mathbb{Q}$  where the stochastic term in Equation (4.2) is governed by Brownian motion or it is a Wiener process. Note that the Feynman-Kac theorem provides the justification for the practice of evaluating today's value of an option ( $V_l(S_0, t_0)$ ) as the discounted expectation of its terminal payoff.

In general, if we assume the volatility  $\sigma(S_t, t)$  is stochastic, Equation (A.12) cannot be solved analytically. However, the situation is a little more tractable if we assume the following: the volatility is a deterministic local volatility  $\sigma(S_t, t)$  and both the risk-free interest rate and dividend yield are deterministic functions. Note that the local volatility  $\sigma(S_t, t)$  should be defined such that it is locally *Lipschitz* and that the *Cauchy-Peano* local existence theorem<sup>8</sup> for ordinary differential equations holds (Duffie, 1996; Hassani, 1991).

To explain this we define  $B(t)$  to be the value of a bank account at time  $t \geq 0$ . We assume  $B(0) = 1$  and that the bank account evolves according to the following differential equation

$$dB(t) = r_t B(t) dt, \quad B(0) = 1$$

where  $r_t$  is a positive function of time (Brigo & Mercurio, 2001). If we integrate we get

$$B(t) = \exp \left( \int_0^t r_u du \right).$$

---

<sup>8</sup>Compare the Picard-Lindelöf theorem or Picard's existence theorem as well

Remember,  $r_u$  is the instantaneous rate at which the bank account accrues in a very short period  $du$ . Note that we integrate over  $[0, t]$ . Following from this we can define the stochastic discount factor  $D(t, T)$  between  $t$  and  $T$  as follows

$$D(t, T) = \frac{B(t)}{B(T)} = \exp\left(-\int_t^T r_u du\right). \quad (\text{A.13})$$

Here,  $D(t, T)$  is the amount at time  $t$  that is equivalent to one unit of currency payable at time  $T$ .

If we now substitute (A.13) into (A.12) and we also assume our contingent claim is a vanilla option with a strike price of  $K$ , we have (we drop the subscript 0)

$$V_l(S, t) = D(t, T)E^{\mathbb{Q}}[\phi(S_T - K)^+ | S_t = S]. \quad (\text{A.14})$$

However, if we assume our risk-free rates are given in continuous compounding format, we have  $D(t, T) = \exp(-r_\tau \tau)$  where  $\tau = T - t$  and thus

$$V_l(S, t) = e^{-r_\tau \tau} E^{\mathbb{Q}}[\phi(S_T - K)^+ | S_t = S]. \quad (\text{A.15})$$

If  $t = 0$  the rate  $r_\tau$  is a zero coupon rate read off from a relevant yield curve. Otherwise  $r_\tau$  is a relevant forward rate that holds from  $t$  to  $T$  and obtained from the zero-coupon yield curve rates for  $t$  and  $T$ . Here,  $\phi$  is an indicator function:  $\phi = 1$  for a call and  $\phi = -1$  for a put.

### A.2. Feynman-Kac in Integral Form

Equation (A.15) is the solution to the local volatility Black-Scholes PDE given in Equation (4.3). However, due to the expectation, it still seems difficult to solve. We also stated that we will use Monte Carlo simulation to solve the Black-Scholes PDE. Monte Carlo simulation is associated with integration. What now?

Remember that the fundamental law of mathematical expectation states: the expectation of a discrete random variable  $X$  is defined as

$$E(X) = \sum_{j=1}^n x_j f(x_j) \quad (\text{A.16})$$

provided the sum is finite (Arnold, 1990). Here  $X$  is a discrete random variable having the possible values  $x_1, x_2, \dots, x_n$  with density function  $f(x_j)$ . We think of  $E(X)$  as the average value of  $X$  — e.g., the average profit in a game of chance. A special case of Equation (A.16) is where all probabilities are equal such that

$$E(X) = \frac{1}{n}(x_1 + x_2 + \dots + x_n).$$

This is of course the arithmetic mean. It acts as a representative or average of the values of  $X$  and is often called a *measure of central tendency* (Spiegel et al., 2000).

For a continuous random variable  $X$  having density function  $f(x)$ , the expectation

of  $X$  is defined as

$$E(X) = \int_{-\infty}^{\infty} xf(x)dx \quad (\text{A.17})$$

where  $x \in \mathbb{R}$  and provided the integral is finite or converges absolutely (Arnold, 1990).

Using the mathematical law of expectation, the expectation for a call option in Equation (A.15) can be written as an integral such that (Duffie, 1996; Wilmott, 2000)

$$V(S, t) = e^{-r_T(T-t)} \int_K^{\infty} \max[0, (S_T - K)]g(S_T)dS_T \quad (\text{A.18})$$

where  $g(S_T)$  is the probability density function (pdf) of  $S_T$  and we assume  $\ln(S_T)$  is normally distributed with a standard deviation of  $w$ . We thus need to integrate over all possible  $S$ -values that is larger than the strike  $K$  at expiry. For a put we have

$$V(S, t) = e^{-r_T(T-t)} \int_0^K \max[0, (K - S_T)]g(S_T)dS_T. \quad (\text{A.19})$$

Remember  $K, S \in \mathbb{R}_0^+$

Under the assumption of a constant volatility and interest rate, the integrals in Equations (A.18) and (A.19) can be solved analytically leading to the well-known Black-Scholes option pricing formulae for calls and puts. However, if we just relax the assumptions of constant volatility and constant interest rate slightly and assume that these two quantities are deterministic (but not constant), the integral cannot be calculated analytically anymore. The integral needs to be solved numerically.

The integral can be solved using Monte Carlo simulation. However, in order to do that, we need to know how  $S_T$  behaves or what the dynamics of  $S_T$  is. This is now quite simple because we know that equations (A.12) and (A.15) are only valid if the asset price dynamics are described by the stochastic differential equation given in (4.2).

### A.3. Integrating the SDE

The stochastic differential equation given in Equation (4.2) describes the dynamics of our stochastic asset price  $S$ . However, we understand this SDE much better if we make a change of variables. Remember, we stated that  $\ln(S_T)$  is normally distributed so let's re-write (4.2) in terms of  $\ln(S)$ . Let's consider the process  $X_t = f(S_t)$  defined by  $f(x) = \ln(x)$  (Clark, 2011). Remember that  $f'(x) = 1/x$  and  $f''(x) = -x^{-2}$ . A simple application of Itô's lemma gives

$$dX_t = (r_t - d_t)dt + \sigma(S_t, t)dW_t - \frac{1}{2}\sigma^2(S_t, t)dt. \quad (\text{A.20})$$

Remember,  $W_t$  is a standard Brownian motion and as such  $dW_t = \varepsilon\sqrt{dt}$  where  $\varepsilon \sim N(0, 1)$ ,  $N(0, 1)$  being a standardised normal distribution. Following from this, Equation (A.20) can be integrated to give

$$X_T = X_0 + \left( (r_T - d_T) - \frac{1}{2}\sigma^2(S_T, T) \right) T + \sigma(S_T, T)\varepsilon\sqrt{T}. \quad (\text{A.21})$$

But,  $X_t = \ln(S_t)$ , thus

$$S_T = S_0 \exp \left( \left( (r_T - d_T) - \frac{1}{2} \sigma^2(S_T, T) \right) T + \sigma(S_T, T) \varepsilon \sqrt{T} \right). \quad (\text{A.22})$$

Equation (A.22) formulates a way to obtain the terminal value of the stochastic process  $S$ . This, together with Equation (A.18) can now be used to obtain the value of our option  $V(S, t)$ .

#### A.4. Discretising the SDE

Equations (4.2) and (A.21) are both defined for a continuous time variable  $t$ . So the question is how do we sample from the continuous distribution for the variable  $S_T$ ? We do not have a mechanism for doing that. In order to model or simulate the security prices in practice we need to discretise the time in the process given in Equation (A.21). In this setting we partition  $[0, T]$  into  $N$  equal subintervals of length  $\Delta t$  and we let (Jäckel, 2002; Hull, 2012)

$$\begin{aligned} dt &\approx \Delta t \\ \Delta t &= \frac{T}{N} \\ dS &\approx \Delta S = S_t - S_{t-1}. \end{aligned}$$

We then simulate  $S$  as a transition over each subinterval  $[t, t + \Delta t]$  by using a discrete first order approximation. We call this an Euler approximation or Euler scheme. Under this first order approximation, Equation (A.21) can be written as follows (Glassermann, 2004)

$$S(t + \Delta t) = S(t) \exp \left[ \left( (r(t) - d(t)) - \frac{\sigma^2(S(t), t)}{2} \right) \Delta t + \sigma(S(t), t) \varepsilon_t \sqrt{\Delta t} \right]. \quad (\text{A.23})$$

The Euler scheme is equivalent to approximating an integral using the left Riemann sum rule for approximating the value of an integral. Hence the integral is approximated as the product of the integrand at time  $t$  and the integration range  $dt$ . The diffusion term in the Euler scheme is  $O(\sqrt{\Delta t})$  and it has strong convergence of order  $1/2$ . This means we can always fall back on this workhorse of a numerical procedure to test any other method (Jäckel, 2002).

Equation (A.23) is called a difference equation meaning the asset price  $S$  at time  $t + \Delta t$  is dependent on the price of  $S$  at a previous time  $t$ . Note, we need the price at a time  $T$ ;  $T \geq t$ .  $S_T$  is obtained by incrementally stepping through time until we get to the  $N$ -th subinterval. We can explain this more clearly if we change subscripts in (A.23) to give

$$S(t_{i+1}) = S(t_i) \exp \left[ \left( (r(t_i) - d(t_i)) - \frac{\sigma^2(S(t_i), t_i)}{2} \right) \Delta t + \sigma(S(t_i), t_i) \varepsilon_t \sqrt{\Delta t} \right]. \quad (\text{A.24})$$

Here,  $i = 1, 2, \dots, N$  such that  $t_i = i\Delta t$  and  $T = N\Delta t$ . In order to start the



simulation we need a starting asset value  $S(t_0)$ . If we then have the input parameters like the volatilities, risk-free rates and dividend yields, we can estimate a price for  $S$  at each discretised step  $i$  until we reach  $S(t_N) = S(T)$ .

The Euler scheme can be improved if we include the next order terms of the Itô-Taylor expansion of Equation (4.1). This gives (Jäckel, 2002; Glassermann, 2004; Clark, 2011)

$$S(t_{i+1}) = S(t_i) \exp \left[ \left( (r(t_i) - d(t_i)) - \frac{\sigma^2(S(t_i), t_i)}{2} [\varepsilon_t^2 - 1] \right) \Delta t + \sigma(S(t_i), t_i) \varepsilon_t \sqrt{\Delta t} \right]. \quad (\text{A.25})$$

By adding a term where the diffusion is  $O(\Delta t)$  we get convergence of strong order 1. One of the advantages of Milstein over Euler time stepping is improved convergence when  $\Delta t$  is infinitesimal. In that case we can take larger time steps and get by with a smaller number of time steps  $N$ .

#### A.5. Now, Monte Carlo Simulation

In section A.2 we asked the question of how one can use Monte Carlo simulation in solving a PDE. We then explained that the solution to the Black-Scholes Equation (4.1) can be written in integral form as shown in Equation (A.15). Integrals can easily be evaluated by Monte Carlo simulation (Robert & Casella, 2004). The discretised version was given in Equation (A.16). If we now discretise equations (A.18) and (A.19) we have (Duffie, 1996; Glassermann, 2004; Jäckel, 2002)

$$V_{MC}(S, t) = e^{-rT(T-t)} \frac{1}{M} \sum_{i=1}^M \max[0, \phi(S_T - K)] \quad (\text{A.26})$$

where  $S_T$  is attained after  $N$  time steps that coincide with the expiry time  $T$ . We can use either Equation (A.24) or Equation (A.25) to estimate  $S_T$ . To obtain the Monte Carlo option price, we need to obtain  $M$ ,  $S_T$  values. This means we simulate  $S_T$ ,  $M$  times to obtain the average option value  $V_{MC}$ . Equation (A.26) is the simplest Monte Carlo approximation of the integral in equations (A.18) and (A.19). Note:  $N$  is the number of time steps and  $M$  the number of simulations.

## B. Random Number Generators (RNG)

Monte Carlo simulation is done by implementing Equation (5.10). However, we need  $S_T$  and we use equations (4.5) and (4.6) for that purpose. From these equations it is evident that we need a random number  $\varepsilon$  that is one of the inputs.  $\varepsilon \sim N(0, 1)$  and is drawn from a standardised normal distribution. In practice the random number is sampled from a discrete distribution calculated by a computer. As such we call these random numbers pseudorandom numbers because they are generated by a computer algorithm utilising mathematical formulae. They are not true random numbers. True randomness can only be obtained from natural phenomena like radiocative decay or atmospheric noise.

Many pseudorandom number generators have been developed over the past few decades. One of the generators used by many practitioners is the Mersenne Twister<sup>9</sup> (Jäckel, 2002). This algorithm has been implemented in many programming languages like C++ and even VBA<sup>10</sup>. Another excellent RNG is the Park-Miller algorithm with Bays-Durham shuffle (Park & Miller, 1988).

Most RNG generate uniform random numbers. This means these numbers are drawn from a uniform distribution. However, we need normal random numbers. The Box-Muller transform is widely used (Jäckel, 2002; Glassermann, 2004).

### C. Monte Carlo Simulation and Convergence

In general, Monte Carlo methods give us at best a statistical error estimate. A Monte Carlo calculation usually follows the following steps: carry out the same procedure many times, take into account all of the individual results, and summarise them into an overall approximation to the problem in question. The approximation is usually the average. The numerically exact solution will be approached only as we iterate the procedure more and more times, eventually converging at infinity (Jäckel, 2002; Glassermann, 2004).

This will be very time consuming so we are not just interested in a method to converge to the correct answer after an infinite amount of calculation time, but rather we wish to have a good approximation quickly. Therefore, once we are satisfied that a particular Monte Carlo method works in the limit, we are naturally interested in its convergence behaviour, or, more specifically, its convergence speed.

Techniques have been developed to reduce the variance of the result and thus to reduce the number of simulations required for a given accuracy. Such techniques are called “variance reduction techniques.”

The most widely used techniques are Antithetic Sampling and Control Variates. Jäckel (2002) and Glassermann (2004) give very good overviews of these techniques.

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<sup>9</sup><http://www.math.sci.hiroshima-u.ac.jp/~m-mat/MT/emt.html>

<sup>10</sup><http://www.math.sci.hiroshima-u.ac.jp/~m-mat/MT/VERSIONS/BASIC/basic.html>

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